



# Introduction to Robotics in CIM Systems (5th Edition)

*James A. Rehg*

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Written from a manufacturing perspective, this book takes readers step-by-step through the theory and application techniques of designing and building a robot-driven automated work cell—from selection of hardware through programming of the devices to economic justification of the project. All-inclusive in approach, it covers not only robot automation, but all the other technology needed in the automated work cell to integrate the robot with the work environment and with the enterprise data base. Robot and other required automation hardware and software are introduced in the order in which they would be selected in an actual industrial automation design. Includes system troubleshooting guides, case studies problems, and worked example problems. Robot Classification. Automated Work Cells and CIM Systems. End-of-Arm Tooling. Automation Sensors. Work-Cell Support Systems. Robot and System Integration. Work-Cell Programming. Justification and Applications of Work Cells. Safety. Human Interface: Operator Training, Acceptance, and Problems. For those interested in Robotics and Manufacturing Automation or Production Design.

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